

Orientalmotor

αSTEP

Hybrid Control System: *αSTEP*



Position, Speed and Torque Control

More Accurate Operation with

Automatic Switching
Between Open Loop and
Closed Loop Control

High Response with No
Hunting or Tuning

What is α STEP?

α STEP is a "hybrid" stepper motor-based motor & driver that together, performs independent control which combines the advantages of "open loop" and "closed loop" performance. In addition to high-accuracy positioning and speed control, it can perform control that restricts the motor's generated torque to a user set value (such as push-motion operation).

Hybrid Control System

The hybrid control system constantly monitors the motors position allowing for the benefits of performance from "open loop" control while providing the assurance of "closed loop" performance.

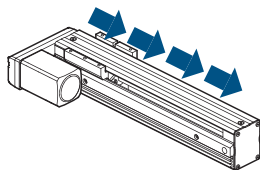
Normal Condition (Positioning deviation is less than $\pm 1.8^\circ$)

Motor is controlled in open loop mode like a stepper motor.

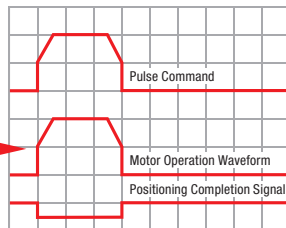
The tuning-free feature allows for high accuracy and high responsiveness to commands

Hunting-free (Complete stop)

Constant monitoring of the motor's status



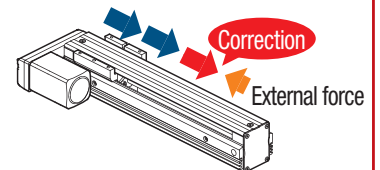
No time lag between command and actual operation



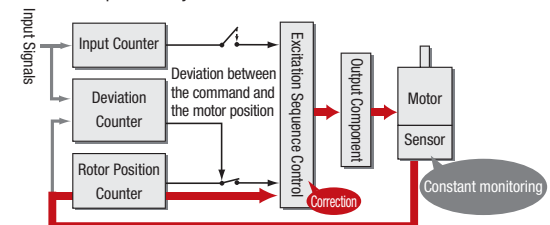
Overload Condition (Positioning deviation is $\pm 1.8^\circ$ min.)

The closed loop mode is engaged to maintain the positioning operation.

Reliability as a result of monitoring and correction of positions and speed

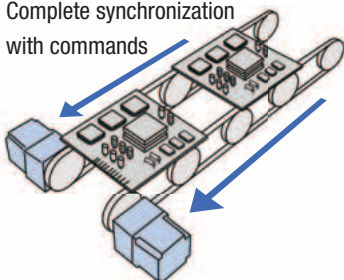


● Closed Loop Control System

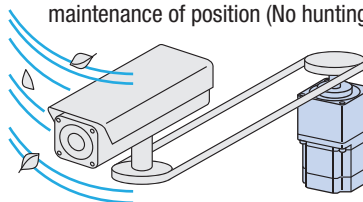


Ideal Applications for α STEP

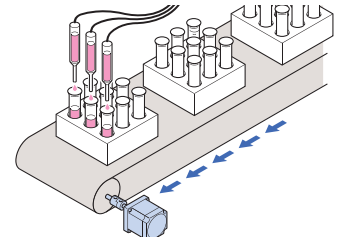
Complete synchronization
with commands



Complete stop during standby and
maintenance of position (No hunting)



Frequent repetitive starting and stopping



Hybrid Control System

Accurate Motion,
Constant Monitoring with
Position Correction

Common Platform with
Motor, Drives, Gears and
Actuators

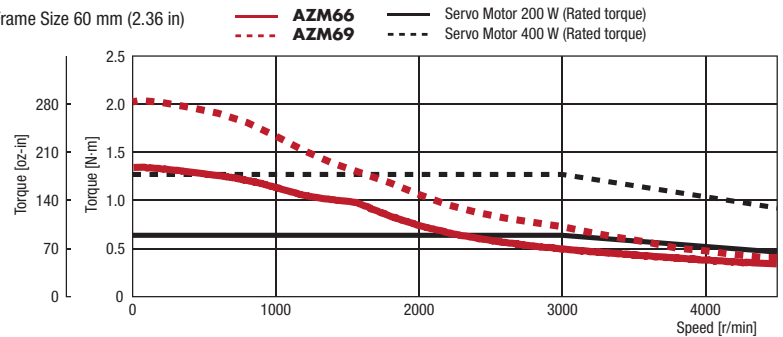
Features of α STEP

What is the Output of α STEP?

“Rated output” is not listed because α STEP has no “rated speed.” Refer to the graph on the right to compare rated torque of α STEP to watts of servo motor’s rated output torque.

- Generates high torque in the mid-to-low speed range
- Excels at frequent starting and stopping operation that requires acceleration/deceleration torque

● Frame Size 60 mm (2.36 in)

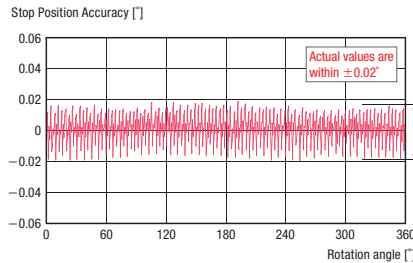


● Data for the speed-torque characteristics is based on Oriental Motor’s internal measurement conditions. If the conditions are changed, the characteristics may also change as a result.

What is the Stopping Accuracy of α STEP?

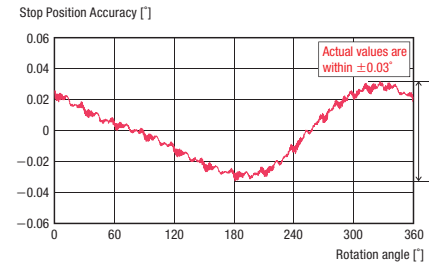
The stopping accuracy of a typical α STEP is $\pm 0.05^\circ$ (under no load), which is equivalent to that of servo motors. The graphs on the right side show the actual measured stopping accuracies when an α STEP and an AC servo motor were rotated once.

● Stopping accuracy of α STEP (Actual measurements)

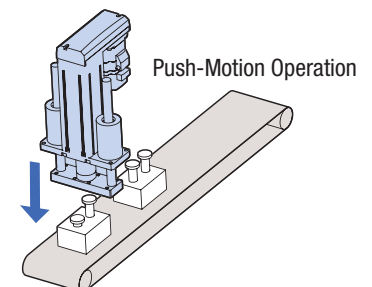
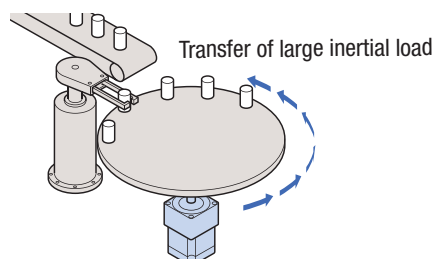
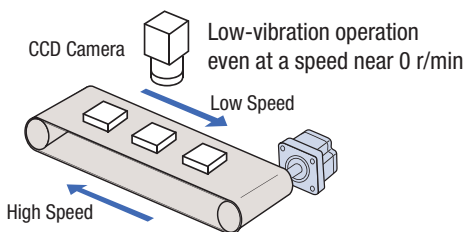


[Example] When the ball screw lead is 10 mm, the α STEP stopping accuracy is $\pm 1.4\mu\text{m}$ and the repetitive positioning accuracy of a common ground ball screw is $\pm 10\mu\text{m}$.

● Stopping accuracy of AC servo motor with a common 20-bit encoder (Actual measurements)



The stopping accuracy of an AC servo motor is the encoder resolution ± 1 pulse*. The above shows the actual values that result from differences in the encoder’s assembly.
*1,048,576 p/rev at 20 bits



Product Variation with the **AZ** Series

Controllability is consolidated across all product groups that contain the **AZ** Series.

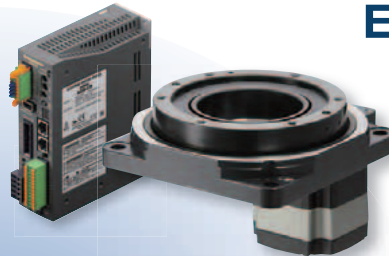
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Printed in USA 19UC 0.70 #515 B