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Item # AZD-KED, AZ Series EtherCAT Compatible Driver (24/48 VDC)



USTEP

AZ Series DC input Stored Data drivers now comes with EtherCAT communications for a battery-free, absolute mechanical sensor motor and driver solution. For use with all Oriental Motor AZ Series motors and linear & rotary actuators equipped with the AZ Ser

Specifications | Communications | Dimensions | System

| pecifications | | |
|---|--|--|
| Lead Time ¹ | Contact your local sales office for product lead-times, available to ship dates and shipping methods. | |
| Driver Type | EtherCAT Compatible | |
| Power Supply | 24/48 VDC | |
| Control Power Supply | 24 VDC ±5%, 0.25 A (0.5 A for Electromagnetic Brake) | |
| Interface - Pulse Input | 2 points, Photocoupler Maximum input pulse frequency Scanner provides line driver output: 1 MHz (50% duty) Scanner provides open collector output:250 kHz (50% duty) | |
| Interface - Control Input | 6 points, Photocoupler | |
| Interface - Pulse Output | 2 points, Line driver | |
| Interface - Control Output | 6 points, Photocoupler/Open collector | |
| Interface - Power Shut Down Signal Input | 2 points, Photocoupler | |

| Interface - Power Shut Down Monitor Output | 1 point, Photocoupler/Open collector | |
|---|--|--|
| Interface - Field Network | EtherCAT | |
| Degree of Protection | IP10 | |
| Insulation Resistance (Driver) | When a 500 VDC megger is applied to the following locations, resistance is $100M\Omega$ or higher. Between the PE terminal and main power supply terminal. | |
| Ambient Temperature Range | 0°C ~ +50°C (+32°F ~ +122°F) (nonfreezing) | |
| Ambient Humidity | 85% max. (noncondensing) | |
| Operating Atmosphere | No corrosive gases or dust. Cannot be used in radioactive area, magnetic field, vacuum or other special environment. | |

Communications

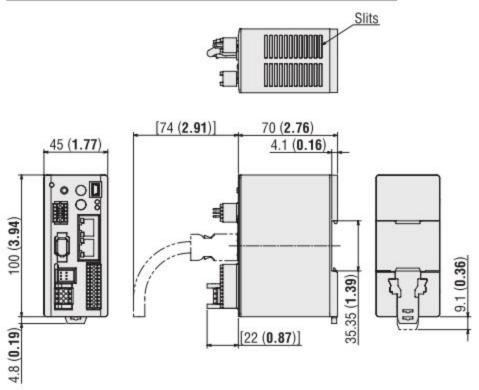
| Communication Standards | IEC 61158 Type12 | |
|-------------------------|--|--|
| Physical Layer | 100 BASE-TX (IEEE 802.3) | |
| Transmission Rate | 100 Mbps | |
| Communication Cycle | Free Run Mode: 1 ms or more SM2 Event Synchronization Mode: 1 ms or more DC Mode: 0.25 ms, 0.5 ms, 1 ms, 2 ms, 3 ms, 4 ms, 5 ms, 6 ms, 7 ms, 8 ms | |
| Communication Port | RJ45x2 (Shielded) ECAT IN: EtherCAT Input ECAT OUT: EtherCAT Output | |
| Topology | Daisy Chain (Up to 65,535 Nodes) | |
| Process Data | Variable PDO Mapping | |
| Sync Manager | SM0: Mailbox Output SM1: Mailbox Input SM2: Process Data Output SM3: Process Data Input | |
| Mailbox (CoE) | Emergency Message SDO Request SDO Response SDO Information | |
| Synchronization Mode | Free Run Mode (Asynchronous) SM2 Event Synchronization Mode DC Mode (SYNC0 Event Synchronization) | |

Dimensions

■ Dimensions Unit: mm (in.)

2D & 3D CAD

| Product Name | Mass kg (lb.) | 2D CAD |
|--------------|------------------|--------|
| AZD-KED | 0.18 (0.40) | B1505 |



Included

Main Power Supply Connector (CN4)

Connector: DFMC1,5/3-ST-3,5-LR (Phoenix Contact)

Control Power Supply Connector (CN1)

Connector: DFMC0,5/5-ST-2,54 (Phoenix Contact)

I/O Signal Connector (CN7)

Connector: DFMC0,5/12-ST-2,54 (Phoenix Contact)

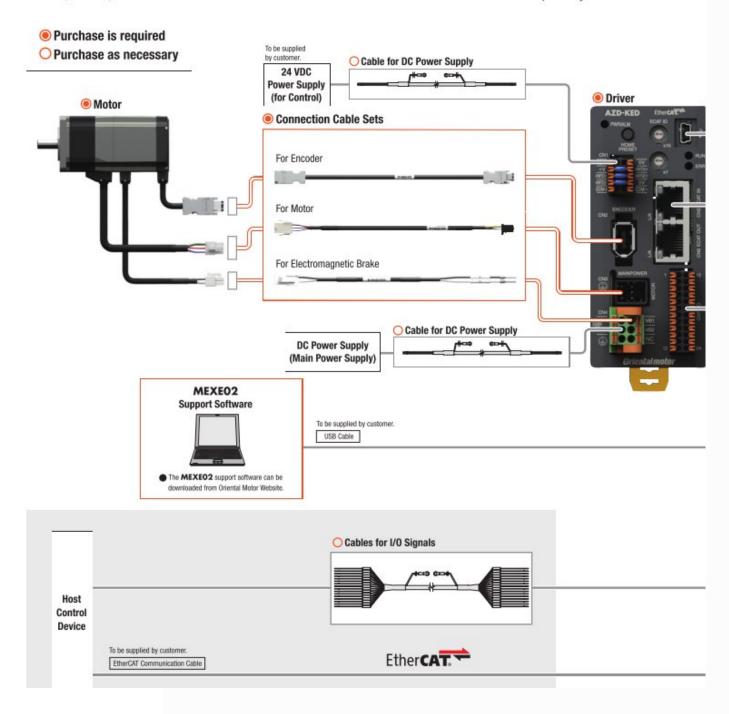
Dimensions

DC Input

■ System Configuration

AZ Series with EtherCAT Drive Profile Compatible Driver

Motors, drivers, and a connection cable set/flexible connection cable set need to be ordered separately.





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